Design and Simulation of MEMS Based Piezoelectric Shear Actuated Beam

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Abstract Now-a-days, there has been growing demand for the development of micro scale devices, due to its less cost, space requirements, high dimensional stability and especially manufacturing time. This paper reports the modeling of MEMS based Piezoelectric shear actuated beam by using COMSOL Multiphysics software of version 4.2a. The dimensions of the model beam is of 100-mm long, 30-mm width, 10-mm thickness. In this paper, we analysed the deflection of beam under different voltages. In the first step, deflection of beam is analysed by changing the material of sandwiched beam. In the second step deflection of beam is explored by changing material of electrodes. In the third step, deflection of beam is analysed by changing both materials of sandwiched beam and electrodes. In the final step deflection of beam is explored by changing both thickness and material of electrodes. Finally, the results of analysis allowed to conclude us to design a piezo electric shear actuated beam with different ranges and resolutions, under the condition of changing both thickness and material of 216nm under 30v excited input voltage.

Keywords MEMS, Sensor, Actuator, Piezoelectric Beam

1. Introduction

MEMS is a process technology used to create tiny integrated devices or systems that combine mechanical and electrical components. They are fabricated using integrated circuit (IC) batch processing techniques and can range in size from a few micrometers to milli meters. These devices (or systems) have the ability to sense, control and actuate on the micro scale, and generate effects on the macro scale[1].

The interdisciplinary nature of MEMS utilizes design, engineering and manufacturing expertise from a wide and diverse range of technical areas including integrated circuit fabrication technology, mechanical engineering, materials science, electrical engineering, chemistry and chemical engineering, as well as fluid engineering, optics, instrumentation and packaging. The complexity of MEMS is also shown in the extensive range of markets and applications that incorporate MEMS devices. MEMS can be found in systems ranging across automotive, medical, electronic, communication and defence applications. Current MEMS devices include accelerometers for airbag sensors, inkjet printer heads, computer disk drive read/write heads, projection display chips, blood pressure sensors, optical switches, micro valves, biosensors and many other products that are all manufactured and shipped in high commercial volumes[2-4]. MEM has been identified as one of the most promising technologies for the 21st Century and has the potential to revolutionize both industrial and consumer products by combining silicon based microelectronics with micromachining technology. Its techniques and micro system based devices have the potential to dramatically affect of all of our lives and the way we live[5-8].

In this paper, we designed and simulated MEMS based piezoelectric shear actuated beam by using COMSOL Multiphysics software of version 4.2a

2. Geometry of Model

The model consists of a 100-mm long sandwiched cantilever beam. This beam is composed of a 2-mm thick flexible foam core sandwiched by two 8-mm thick aluminium layers. Further, the device replaces part of the foam core with a 10-mm long piezoceramic actuator that is positioned between x=55 mm and x=65 mm. The cantilever beam is orientated along the global x-axis.

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Figure 1. Geometry of model

• Structural mechanics: the cantilever beam is fixed at its surfaces at x = 0; all other surfaces are free.

• Electrostatics: The system applies a 20 V potential difference between the top and bottom surfaces of the piezoceramic domain. This gives rise to an electric field perpendicular to the poling direction (x direction) and thus induces a transverse shear strain.

2.1. Material Properties

The following table gives the properties of materials used in the model:

Property	Aluminium	Copper	Foam	Lead zirconate titan ate	Barium titanate
Young's modulus	70 GPa	120 GPa	35.3 MPa	-	-
Poisson's ratio	0.35	0.34	0.383	-	-
Density	2700 kg/m3	8960 kg/m3	32 kg/m3	7500 kg/m3	6020 kg/m3

Table 1. Material properties

Aluminium:

• Ductility & Malleability: High

• The property relating to how easily deformation occurs. Aluminium is both very malleable, and very ductile. In fact aluminium is the 2nd most malleable metal, and the Hardness:420 Mpa

Hardness is the ability to not be easily scratched, in is measured in Pascals or force per unit area. 6th most ductile, both of these are very important for its uses.

• Electrical Resistivity: Low 2.65 x 10⁻⁸ Ohm metres

Aluminium has a very low electrical resistivity, and therefore a high electrical conductivity. This is measured in Ohms meters, as resistivity is equal to the resistance of a certain sized piece of the material multiplied by the area and divided by the length.

COPPER:

•Thermal conductivity: The thermal conductivity of copper, 394W/mK, is about twice that of aluminium and thirty times that of stainless steel. This means that copper is used for components where rapid heat transfer is essential.

•Corrosion resistant: copper is non-reactive and does not rust or become brittle in sunlight.

•High ductility: Tubes are easily bent even when hard

•High resistance: withstands fire well, melting point is 1083°C

Bariun titanate

•Barium titanate is the inorganic compound with the chemical formula BaTiO₃. It is a white powder and transparent as larger crystals.

•Barium titanate goes through two phase transitions that change the crystal shape and volume. This phase change leads to composites where the barium titanates have a negative bulk modulus (Young's modulus), meaning that when a force acts on the inclusions, there is displacement in the opposite direction, further stiffening the composite.

•It is used in microphones and transducers.

Lead zirconate titanate

•Lead zirconate titanate is an inorganic compound with the chemical formula $Pb[Zr_xTi_{1-x}]O_3 \ 0 \le x \le 1$). Also called **PZT**, it is a ceramic perovskite material that shows a marked piezoelectric effect, which find practical applications in the area of electro ceramics.

2.2. Design Procedure

The modeling mems based piezoelectric shear actuated beam is done in the COMSOL MULTIPYSICS software. In this, first piezoelectric devices present in structural mechanics module in the ADD PHYSICS tree. Then we have to select STUDIES in preset studies. The next step is to construct geometry of the beam, which consists of three blocks of 100-mm long each with different thickness. The next step is to define co-ordinate system as base vector system. The next is to do physical interface i.e., to add material to that model and to specify values of properties of that materials. Then we have defined fixed constraints, electric potential and ground boundaries. Then mesh of the model has to build. Then compute the model by and get displacement plot as follows:

The same model can be simulate by changing voltages, materials and can observe for displacement plots.

2.3. Simulations

The following simulations are done on the model of piezoelectric shear actuated beam:

▲ 83.02 80 $^{>}0.1$ 0.015 40 0.01 30 0.005 n 0.05 20 10 n nì 0 0 0 ▼ -0.072

Surface: Displacement field, z component (nm) Surface Deformation:

Figure 2. Deflection plot

2.3.1. Simulation-1 for Pzt-5h and Al

In this pzt-5h as piezoceramic material and aluminium as electrodes are taken and compute by applying 10V, 20V, 30v. The displacement plots are as follows:



Figure 3. Deflection plot for simulation-1

2.3.2. Simulation-2 for Pzt-5h and Cu

In this pzt-5h as piezoceramic material and copper as electrodes are taken and compute by applying 10V, 20V, 30v. The displacement plots are as follows:



2.3.3. Simulation-3 for Barium Titanate and Cu

In this barium titanate as piezoceramic material and copper as electrodes are taken and compute by applying 10V, 20V, 30v. The displacement plots are as follows:



2.3.4. Simulation-4 for Barium Titanate and Al

In this barium titanate as piezoceramic material and aluminium as electrodes are taken and compute by applying 10V, 20V, 30v. The displacement plots are as follows:



2.3.5. Simulation-5 for Pzt-5h and Cu with 4-Mm Thickness

In this pzt-5h as piezoceramic material and 4-mm thickness copper as electrodes are taken and compute by applying 10V, 20V, 30v. The displacement plots are as follows:



Figure 7. Deflection plot for simulation-5

Table 2.	Comparison	between	existing	model	and ne	ew model
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	Material for piezoceramic	Material for electrodes	For 10V input	For 20V input	For 30V input
For existing model	PZT-5H (2-mm thickness)	Aluminium (8-mm thickness)	41.5nm	83nm	124.5nm
For new model	Barium titanate (2-mm thickness)	Copper (8-mm thickness)	22.4nm	44.8nm	67.8nm
For new model	PZT-5H (2-mm thickness)	Copper (4-mm thickness)	69.8nm	139.8nm	216.7nm

3. Results and Discussions

The analysis from the above table is as follows:

•With increase in voltage the deflection of the beam increases but beyond 30V the model becomes unstable. So we can apply voltage up to 30V.

•The piezoceramic material, lead zirconate titanate gives high shear than any other piezoceramic material and also with decrease in the thickness of electrodes and using copper, high electrical conductivity material than aluminium gives maximum shear in the beam.

• Thus, for the application of actuator, which requires deflection particularly 216nm, this model with piezoceramic material of PZT-5H of 2-mm thickness and copper electrodes of 4-mm thickness can be used.

The deflection plot with optimum displacement is as follows;



4. Conclusions

The conclusion to this paper is that with the model-"PIEZOELECTRIC SHEAR ACTUATED BEAM" having 4-mm thickness of copper electrodes and 2-mm thickness PZT-5H when excited by 30v gives optimum deflection of 216 nm when compared to the model of 8-mm thickness aluminium electrodes and 2-mm thickness PZT-5H when excited by 20v gives a deflection of 83 nm. The material selection and dimensions of a user specific mems based Piezo electric shear actuated beam are selected with optimized range and resolution. Thus this actuating operation finds a usage specifically in an application which needs a deflection of 216nm.

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