Rapid Approach to Resolving the Adequacy Problem of Mathematical Modeling of Physical Phenomena by the Example of Solving One Problem of Hydrodynamic Instability

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Abstract The linear stability problem of steady-state plane-parallel shear flows of a continuously stratified in density inviscid incompressible fluid in the gravity field between two immovable impermeable solid parallel planes in the Boussinesq approximation is studied. With the use of the direct Lyapunov method, it is proved that from the theoretical consideration (on semi-infinite temporal intervals) these flows are absolutely unstable with respect to small plane perturbations. Namely, a priory lower estimate is constructed; the estimate displays exponential in time growth of the considered perturbations. At that increment of containing in this estimate exponent is any positive constant. Using the direct Lyapunov method, constructive sufficient conditions of practical instability (on finite temporal intervals) are also found for these flows with respect to small plane perturbations.

Keywords an Ideal Stratified Fluid, the Boussinesq Approximation, Steady-State Plane-Parallel Shear Flows, the Direct Lyapunov Method, an Absolute Theoretical Instability, a Priory Lower Estimate, Conditions of Practical Instability

1. Introduction

The stability problem of steady - state plane-parallel shear flows of a continuously stratified in density inviscid incomp ressible fluid in the gravity field in the Boussinesq approxi mation with respect to small plane perturbations is one of fundamental problems in hydrodynamics, meteorology, ocea nography and other related fields of science[1], has not lost its urgency in our time too. The most important application of this mathematical model in practice is the description of processes of wave motions propagation on reservoirs surfac es, when density distributions weakly differ from constant values, vertical scales of movements are small compared with characteristic depths, and Mach numbers are much smaller than unity.

Basic results on stability studying of steady-state planeparallel shear flows of a continuously stratified in density inviscid incompressible fluid in the gravity field between

Published online at http://journal.sapub.org/ijtmp

two immovable impermeable solid parallel planes in the Boussinesq approximation with respect to small plane pertu rbations are found by spectral method with use of integral relations[2–4]. Unfortunately, these results are correct just for perturbations as normal modes[1, 4]. Moreover, the cons equence of integral ratios application is that all admissible perturbations as normal modes are not really taken into account, but only those that satisfy the additional requireme nt to Taylor-Goldstein differential operator[2–4].

At last, as follows from energy reasoning given in work[5], in theoretical sense only states of rest with fluid density increasing towards the bottom plane are stable with respect to such subclass of small plane perturbations that for it small perturbations of studied fluid density are equal to zero on boundary. However, imposing of arbitrarily weak shear of fluid velocity destabilizes these rest states. Moreover, except for states of rest considered in article[5], it isn't possible to find conditions of theoretical stability for any steady-state flows of studied fluid with respect to small plane perturbati ons by means of energy reasons.

All this pushes to make the assumption that there is an absolute theoretical instability of steady-state plane-parallel shear flows of a continuously stratified in density inviscid

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incompressible fluid in the gravity field in the Boussinesq approximation with respect to small plane perturbations. If this assumption is confirmed, it will mean that the mathema tical model of a continuously stratified in density inviscid incompressible fluid in the Boussinesq approximation descr ibes steady-state plane-parallel shear flows in the gravity field inadequately.

Extended above assumption of absolute instability of the studied steady-state plane-parallel shear flows in theoretical sense can be verified by the direct Lyapunov method[6–8] — the most powerful analytical method of the mathematical th eory of hydrodynamic stability. However, the main difficulty with using this method is that until now regular ways for construction of growing Lyapunov functionals have been unknown.

Fortunately, the analytical technique[6] which allows to receive results and about theoretical (on semi-infinite intervals of time), and about practical (on finite temporary intervals) instability of those or other considered steady-state flows of fluids, gases or plasma with respect to small plane perturbations has been offered recently. The main point of the new technique consists in algorithmic constructing of Lyapunov functionals, being characterized, on the one hand, monotonous growth over time in chime with properties of solutions to the corresponding initial-boundary value proble ms for small perturbations, and the other - such dependence form on small perturbations that growth of small perturbatio ns over time according to Lyapunov definition of instability [7] follows from increase of these functionals in time. At that, arising conditions for Lyapunov functionals increase with time just will be desirable sufficient conditions for either theoretical or practical instability of studied flows with respect to small plane perturbations. It is remarkable that for application of this technique it isn't necessary to know the specific type of solutions to the boundary and/or the mixed problems which describe the studied flows and perturbation s[6].

Thus, in this work absolute instability in theoretical sense will be proved by the direct Lyapunov method[6–8] for steady-state plane-parallel shear flows of a continuously stratified in density inviscid incompressible fluid in the gravity field between two immovable impermeable solid parallel planes in the Boussinesq approximation with respect to small plane perturbations. Besides, a priory lower estimate which will show exponential growth over time of the considered small perturbations will be constructed. At last, constructive sufficient conditions of practical instability for the studied flows with respect to small plane perturbations will be received.

2. Formulation of the Exact and the Linearized Problems

Unsteady-state plane flows of an ideal heterogeneous in density incompressible fluid in the gravity field between two immovable impermeable solid parallel planes in the Boussinesq approximation are considered. In a consent with this approximation, we neglect density changes when it concerns their influence on inertia, but, by no means, not weight changes (or buoyancy) of fluid [9].

These flows are described by evolutionary solutions to the initial-boundary value problem [1-3, 9]

$$\hat{\rho}_0 D u = -p_x, \ \rho_0 D v = -p_y - \rho g, \ D\rho = 0, \ u_x + v_y = 0 \text{ in } \tau;$$

$$v = 0 \text{ on } \partial \tau; \qquad (1)$$

$$u(x, y, 0) = u_0(x, y), v(x, y, 0) = v_0(x, y),$$

where $\hat{\rho}_0$ is a constant average density of fluid, $\rho(x, y, t)$ — its perturbations; u(x, y, t), v(x, y, t) are components of the fluid velocity field; p(x, y, t) is the pressure field perturbations; $\nabla \Phi = (0, g), g \equiv \text{const}$ — the potential field of gravity; $D = \partial / \partial t + u \partial / \partial x + v \partial / \partial y$ is a differential operator; x, y are Cartesian coordinates; $\tau = \{(x, y): -\infty < x < +\infty, 0 < y < H\}$ is the domain of fluid flow; $\partial \tau = \{(x, y): -\infty < x < +\infty, y = 0, H\}$ — its boundary; u_0 , v_0 are the initial components of the fluid velocity field; t is the time; $H \equiv \text{const}$ — the width of the gap between the walls. Independent variables as subindexes stand for partial derivatives of desired functions. As assumed, the initial components u_0 and v_0 of the fluid velocity field turn the fourth relation of the mixed problem (1) into the identity. Moreover, v_0 is assumed to satisfy the fifth relation in the same problem.

If solutions to the initial-boundary value problem (1) are periodic or located along x-axis, this problem possesses the energy integral in the form

$$E_1 \equiv \int_{-\infty}^{+\infty} \int_{0}^{H} \left(\hat{\rho}_0 \frac{u^2 + v^2}{2} + \rho \Phi \right) dx dy = \text{const}.$$
 (2)

Moreover, the mixed problem (1) possesses one more integral of motion. Really, by means of introducing into consideration the function $\lambda(x, y, t)$, which retains its values in any fluid particle as it moves ($D\lambda = 0$), the integral

$$I \equiv \int_{-\infty}^{+\infty} \int_{0}^{H} F(\lambda) dx dy = \text{const},$$
 (3)

where $F(\lambda)$ is an arbitrary function of its argument, stays a constant one on evolutional solutions to the initial-boundary value problem (1).

The mixed problem (1) has exact stationary solutions of the form

$$\rho = \rho_0(y), \ u = U(y), \ v = 0, \tag{4}$$

$$p = P(y) \equiv p_0 - \int_0^y \rho_0(y_1) \frac{d\Phi}{dy_1} dy_1$$

(here ρ_0 , U are an arbitrary functions in independent variable y, p_0 is an additive constant, y_1 is a integration variable). These solutions correspond to the steady-state plane-parallel shear flows of a continuously stratified in density inviscid incompressible fluid in the gravity field between two immovable impermeable solid parallel planes in the Boussinesq approximation.

Further consideration is aimed to answer the question if the stationary solutions (4) can be stable ones with respect to small plane perturbations.

With this aim in mind, we linearize the initial-boundary value problem (1) in the vicinity of the exact stationary solutions (4) and finally arrive at the mixed problem:

$$\hat{\rho}_{0}\left(u'_{t}+Uu'_{x}+v'\frac{dU}{dy}\right) = -p'_{x},$$

$$\frac{\partial\rho'}{\partial t}+U\rho'_{x}+v'\frac{d\rho_{0}}{dy} = 0, \quad \hat{\rho}_{0}\left[\frac{\partial v'}{\partial t}+U\frac{\partial v'}{\partial x}\right] = -p'_{y}-\rho'g,$$

$$u'_{x}+v'_{y}=0 \quad \text{in} \quad \mathcal{T};$$

$$v'=0 \quad \text{on} \quad \partial\tau;$$

$$u'(x,y,0) = u'_{0}(x,y), \quad v'(x,y,0) = v'_{0}(x,y),$$
where $v'(x,y,0) = v'_{0}(x,y), \quad v'(x,y,0) = v'_{0}(x,y),$

where $u'(x, y, t), v'(x, y, t), \rho'(x, y, t), p'(x, y, t)$ are small plane perturbations of velocity u, v, density ρ , and pressure p fields, u'_0, v'_0 are the initial components of the perturbed field of fluid velocity. As assumed, the function v'_0 , firstly, turns the fifth relation of the initial-boundary value problem (5) into the identity and, secondly, satisfies the fourth relation of the same problem together with the function u'_0 .

Unfortunately (at least, as of today), the linear analogue of the energy integral for the mixed problem (5) has not yet been detected by means of the energy considerations.

3. A Priori Exponential Lower Estimate for Growth of Small Plane Perturbations

Next, by the direct Lyapunov method it will be proved that steady-state flows (4) are absolutely unstable in theoretical consideration with respect to small plane perturbations (5).

In order to demonstrate theoretical instability of a stationa ry solution (4) of the initial-boundary value problem (1) with respect to small plane perturbations (5) we need at least one of these perturbations, but with the exponential time growth.

From the above reasoning, the desired perturbation is sought in such subclass of plane flows that its small plane perturbations (5) are deviations of fluid particles motion paths from the corresponding stream lines of steady-state flows (4). The easiest description for these perturbations can be obtained with the use of the Lagrangian displacements field $\xi(x, y, t) = (\xi_1, \xi_2)[10]$ which is given by the equations

$$\xi_{1t} = u' - U\xi_{1x} + \xi_2 \frac{dU}{dy}, \ \xi_{2t} = v' - U\xi_{2x}.$$
(6)

In view of the relations (6), the mixed problem (5) can be rewritten in the form:

$$\hat{\rho}_{0}\left(\xi_{1tt} + 2U\xi_{1tx} + U^{2}\xi_{1xx}\right) = -p'_{x}, \ \xi_{1x} + \xi_{2y} = 0, \quad (7)$$

$$\hat{\rho}_{0}\left(\xi_{2tt} + 2U\xi_{2xt} + U^{2}\xi_{2xx}\right) = -p'_{y} + \frac{d\rho_{0}}{dy}g\xi_{2};$$

$$\xi_{2} = 0 \text{ on } \partial\tau;$$

$$\xi_{1}(x, y, 0) = \xi_{10}(x, y), \quad \xi_{1t}(x, y, 0) = (\xi_{1t})_{0}(x, y),$$

$$\xi_{2}(x, y, 0) = \xi_{20}(x, y), \quad \xi_{2t}(x, y, 0) = (\xi_{2t})_{0}(x, y)$$

(here ξ_{10}, ξ_{20} are the initial components of the Lagrangian displacements field ξ ; $(\xi_{1t})_0$ and $(\xi_{2t})_0$ are the initial components of its first order time partial derivative). As assumed, the functions ξ_{10}, ξ_{20} turn the second equation of the system (7) into the identity. Moreover, the function ξ_{20} is assumed to satisfy the fourth equality in the same system.

In the subclass (6) linear analogue of energy integral for the initial-boundary value problem (7) are represented by next form

$$E = \frac{1}{2} \int_{-\infty}^{+\infty} \int_{0}^{H} \left[\hat{\rho}_{0} \left(\xi_{1t} + U\xi_{1x} \right)^{2} + \rho_{0} \left(\xi_{2t} + U\xi_{2x} \right)^{2} - \frac{2\hat{\rho}_{0} U \left(\xi_{1x}\xi_{1t} + \xi_{2x}\xi_{2t} \right) - \frac{2\hat{\rho}_{0} U^{2} \left(\left(\xi_{1x} \right)^{2} + \left(\xi_{2x} \right)^{2} \right) - \frac{d\rho_{0}}{dv} g \left(\xi_{2} \right)^{2} \right] dy dx.$$

$$(8)$$

Indeed, by direct calculations it isn't hard to obtain that the first variation δJ of integral $J \equiv E_1 + I$ (2), (3) is equal to zero on stationary solutions (4) if and only if by choosing of function $\lambda = \lambda(\rho)$ form the first variation of density perturbations on boundary $\delta \rho |_{\partial \tau}$ becomes equal to zero.

At the same time, the second variation $\delta^2 J$ of integral J is coincident in the form with functional E (8)[5].

The integrand expression (8) has the constant-sign property only on states of rest and only when the following condition on density distribution of considered fluid $d\rho_0/dy \le 0$ is satisfied. Superimposing arbitrarily weak speed shift destabilizes rest states in the sense that the constant-sign of integrand expression (8) is broken. As a result, the stability condition for steady-state flows (4) with respect to small pla- ne perturbations (6), (7) doesn't exist. It is significant that lo- cal Richardson number $R i = -(g/\hat{\rho}_0)(d\rho_0/dy)(dU/dy)^{-2}$ doesn't appear in coefficients of integrand expression (8). This fact maintains that local Richardson number doesn't arise as the stability condition from energetic reasoning[5].

To further study, it is convenient to use the linear analogue of energy integral (8) in the form

$$E \equiv T + T_1 + \Pi = \text{const},\tag{9}$$

where

$$T = \frac{1}{2} \hat{\rho} \int_{-\infty}^{+\infty} \int_{0}^{+\infty} \int_{-\infty}^{H} \left[\left(\xi_{1t} + U\xi_{1x} \right)^2 + \left(\xi_{2t} + U\xi_{2x} \right)^2 \right] dy dx \ge 0,$$

$$r_1 = -\hat{\rho} \int_{-\infty}^{+\infty} \int_{0}^{H} \left[U(\xi_{1x}\xi_{1t} + \xi_{2x}\xi_{2t}) + U^2 \left((\xi_{1x})^2 + (\xi_{2x})^2 \right) \right] dy dx,$$

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$$\Pi = -\frac{1}{2} \int_{-\infty}^{+\infty} \int \frac{d\rho_0}{dy} g \xi_2^2 dy dx,$$

and also to introduce into the presentation an auxiliary functional in form[6]

$$M \equiv \hat{\rho}_0 \int_{-\infty}^{+\infty} \int_{0}^{H} \left(\xi_1^2 + \xi_2^2\right) dy dx.$$
 (10)

Actually, if we differentiate the integral M(10) by its argument t twice, transform the result with the use of relations (6), (7), and (9), it is not hard to arrive at the so-called virial equality[10]

$$\frac{d^2M}{dt^2} = 4(T - \Pi).$$
 (11)

It should be noted that by arbitrary constant value λ the non-negative functional can be constructed of integrals T, M, and dM/dt in the form

$$2T_{\lambda} \equiv 2T - \lambda \frac{dM}{dt} + \lambda^2 M =$$
(12)

$$= \hat{\rho}_0 \int_{-\infty}^{+\infty} \int_{0}^{H} \left(\left(\xi_{1t} + U\xi_{1x} - \lambda\xi_1 \right)^2 + \left(\xi_{2t} + U\xi_{2x} - \lambda\xi_2 \right)^2 \right) dy dx \ge 0.$$

Excepting integral T from expression (12) by relation (11) and using notation $\alpha \equiv g \max_{0 \leq y \leq H} |d\rho_0 / dy|$, it is possible

to construct the differential inequality in form

$$\frac{d^2M}{dt^2} - 2\lambda \frac{dM}{dt} + 2(\lambda^2 + \alpha)M \ge 0.$$
(13)

Now, if constant value λ is satisfied to the requirement $\lambda > 0$, and, by analogy to monographs[6, 11], supplemental conditions in the form

$$M\left(\pi n / 2\sqrt{\lambda^2 + 2\alpha}\right) > 0; \quad n = 0, 1, 2, ...; \quad (14)$$

$$\frac{dM}{dt} \left(\pi n / 2\sqrt{\lambda^2 + 2\alpha} \right) \ge 2(\lambda + \alpha / \lambda) M \left(\pi n / 2\sqrt{\lambda^2 + 2\alpha} \right);$$

$$M \left(\pi n / 2\sqrt{\lambda^2 + 2\alpha} \right) \equiv M(0) exp \left(\pi n \lambda / 2\sqrt{\lambda^2 + 2\alpha} \right),$$

$$\frac{dM}{dt} \left(\pi n / 2\sqrt{\lambda^2 + 2\alpha} \right) \equiv \frac{dM}{dt} (0) exp \left(\pi n \lambda / 2\sqrt{\lambda^2 + 2\alpha} \right)$$

are added to the equation (13) that from it, under these conditions, the desired a priori exponential on the time lower estimate

$$M(t) \ge C \exp(\lambda t) \tag{15}$$

will arise with the need (here C is the known positive constant).

It is worth noting that the class of the mixed problem (6), (7) solutions, which grow with time in accordance with the constructed estimate (15), with an additional conditions

$$M(0) > 0, \quad \frac{dM}{dt}(0) \ge 2(\lambda + \alpha / \lambda)M(0) \tag{16}$$

on the initial data $\xi_0(x, y)$ and $(\xi_t)_0(x, y)$ is not empty: 1) since the initial-boundary value problem (6), (7) is linear, then it is solvable with respect to small plane perturbations in the form of normal waves[4, 11]; 2) as the functional E (8) has not the constant-sign property, the mixed problem (6), (7) is also solvable with respect to the rising over time small plane perturbations in the form of normal waves[6, 11]; 3) every growing with time solution of the initial-boundary value problem (6), (7), corresponding to the small plane disturbance in the form of normal wave, will be, due to arbitrariness of positive constant λ , satisfy the differential inequality (13), the countable set of conditions (14) and the lower estimate (15) identically and automatically[6, 11].

Consequently, there are increasing in time solutions to the mixed problem (6), (7), (16), which meet the small plane perturbations in the form of normal waves, in fact.

In turn, the relation (15) demonstrates graphically that, according to the Lyapunov definition of instability[7], as minimum, one small plane perturbation (6), (7), (16) of steady-state plane-parallel shear flows (4) of an ideal stratified fluid grows over time, at that not slower than exponentially. Since this relation is obtained without involvement of any requirements of a restrictive nature to steady-state flows (4), it is precisely this fact that testifies to the absolute theoretical instability of the latter with respect to small plane perturbations (6), (7), (16).

It is also worth noticing that in the given paper the integral M (10) exactly serves as the Lyapunov functional which grows in time in accordance with the motion equations of the initial-boundary value problem (6), (7), (16). The distinctive feature of this growth represents a lot of freedom, which is preserved for the positive constant λ in the exponent from the right part of the lower estimate (15). This freedom, among other things, allows us to interpret every solution of the mixed problem (6), (7), (16), which increases with time according to the found priori exponential lower estimate (15), as an analogue of Hadamard example for incorrectness[12].

Finally, for small plane perturbations (6), (7), (16) inequa lities of relations system (14) are sufficient conditions for practical linear instability[13, 14] of steady-state planeparallel shear flows (4) of inviscid stratified fluid, but for small plane perturbations (6), (7), (16) in the form of normal waves — necessary and sufficient (thanks to the fact that the positive constant λ is arbitrary one as for the rest).

It is also important that these conditions for practical line ar instability are characterized by constructiveness, allowing their use for the purposes of testing and control during physi cal experiments and numerical calculations.

Indeed, let, for example, we need to develop a technologi cal process, which is based on the use of steady-state flows (4).

In order for this process to be reliable in operation, it is necessary to ensure its practical stability with respect to all possible disturbances. In particular, this process must be stable in a practical sense with respect to small plane pertur bations (6), (7), (16) in the form of normal waves.

This result can be achieved by construction the numerical model, which corresponds to the linearized initial-boundary

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value problem (6), (7), (16), with the control in reference temporal points $t_n \equiv \pi n/2\sqrt{\lambda^2 + 2\alpha}$ (n = 1, 2, 3, ...) for the truth of the inequalities from the relations system (14). In the course of this model construction, it requires main efforts to focus on the fact that the inequalities of the relations system (14) were not valid because of those or other artificially induced external influences on the unsteady-state flows (6), (7) (for example, due to the initial conditions (16) violation).

In the end, the practical stability of the developed technological process will be guaranteed, at the least, with respect to small plane perturbations (6), (7), (16) in the form of normal waves.

Unfortunately, to date, the problem of constructing the numerical model described above has not been solved yet and so far only waits for the moment when specialists will turn their attention on it.

Finally, it will be realized the comparison of this article results with the well-known result of the stability spectral theory for steady-state plane-parallel shear flows of a continuously stratified in density inviscid incompressible fluid in the gravity field between two immovable impermeable solid parallel planes in the Boussinesq approximation, which was obtained earlier by the integral relations method for the small plane perturbations in the form of normal waves — the Miles theorem[2–4].

4. The Miles Theorem

Evolutionary solutions to the mixed problem (6), (7) of the form

$$\xi_1(x, y, t) \equiv f_1(y) \exp(ik(x - ct)), \qquad (17)$$

$$\xi_2(x, y, t) \equiv f_2 \exp(ik(x - ct)), \qquad (17)$$

$$p'(x, y, t) \equiv f_3(y) \exp(ik(x - ct))$$

(here f_1, f_2 , and f_3 are arbitrary functions of its argument; *i* is the imaginary unit; $c \equiv c_r + ic_i$, an arbitrary complex constant; k, c_r, c_i are arbitrary real constants) are considered.

Substituting the relations (17) into the motion equations and the boundary condition of system (7), we conclude that the functions ξ_1, ξ_2 , and p' of the form (17) indeed satisfy the initial-boundary problem (6), (7) if the functions f_1, f_2 , and f_3 are solutions to the system of ordinary differential equations

$$(c-U)^2 k f_1 \hat{\rho}_0 = i f_3,$$
 (18)

$$(c-U)^{2}k^{2}f_{2}\hat{\rho}_{0} = \frac{df_{3}}{dy} - g\frac{d\rho_{0}}{dy}f_{2}, \quad ikf_{1} + \frac{df_{2}}{dy} = 0$$

supplemented by the boundary conditions

$$f_2 = 0 \text{ on } y = 0, H.$$
 (19)

Excluding the functions f_1 and f_3 from the system (18), we can obtain the so-called Taylor-Goldstein equation[2, 4] for the function f_2 :

$$\frac{d^2 f_2}{dy^2} - \frac{2}{c-U} \frac{dU}{dy} \frac{df_2}{dy} - \left(k^2 + \frac{1}{(c-U)^2} \frac{g}{\hat{\rho}} \frac{d\rho}{dy}\right) f_2 = 0. (20)$$

Including the new dependent variable

 $f(y) \equiv (c - U)f_2,$

we obtain the final version of the boundary value problem (19), (20):

$$\frac{d^2 f}{dy^2} + \left(\frac{d^2 U/dy^2}{c - U} - k^2 - \frac{d\rho_0/dy}{\hat{\rho}_0} \frac{g}{(c - U)^2}\right) f = 0; \quad (21)$$

$$f = 0 \quad \text{on} \quad y = 0, H.$$

Following Miles, we need to make yet another substitution of the sought function $f(y) \equiv (U(y)-c)^{1/2}h(y)$, and the received after this substitution relation to multiply by the complex-conjugate function h^* and to separate its imaginary part:

$$c_{i}\left(-\left|\frac{dh}{dy}\right|^{2}-k^{2}\left|h\right|^{2}+\frac{\left|h\right|^{2}}{\left|U-c\right|^{2}}\left(\frac{1}{4}\left(\frac{dU}{dy}\right)^{2}+\frac{g}{\hat{\rho}_{0}}\frac{d\rho_{0}}{dy}\right)\right)=$$
$$=Im\left[\frac{d}{dy}\left((U-c)h^{*}\frac{dh}{dy}\right)\right].$$
(22)

Approved by[2-4] that the equality (22) integration over the layer cross-section between two immovable impermeable solid parallel planes with the use of boundary conditions (21) gives the relation in the form

$$c_{i} \int_{0}^{H} \frac{|h|^{2}}{|U-c|^{2}} \left(\frac{1}{4} \left(\frac{dU}{dy} \right)^{2} + \frac{g}{\hat{\rho}_{0}} \frac{d\rho_{0}}{dy} \right) dy =$$
(23)
$$= c_{i} \int_{0}^{H} \left(\frac{|dh|}{dy}^{2} + k^{2} |h|^{2} \right) dy > 0.$$

From this relation it follows that the exponentially growing ($c_i > 0$) small plane perturbations (6), (7) in the form of normal waves (17) are able to convert it into an identity if and only if $Ri < \frac{1}{4}$ at least at one point within the domain of the fluid flow.

In the end, it is established the sufficient condition

$$R i \ge \frac{1}{4} \tag{24}$$

for the theoretical stability of the exact stationary solutions (4) to the mixed problem (1) with respect to small plane perturbations (6), (7) in the form of normal waves (17) (the Miles theorem[2-4]).

However, as it is demonstrated below, the ratio (23) follows from equation (22) not for all functions h.

In fact, if the integral of the right-hand part of the equality (22) is rewritten in the form

$$\int_{0}^{H} Im \left(\frac{d}{dy} \left[(U-c)h^* \frac{dh}{dy} \right] \right) dy =$$
(25)

(26)

$$= \operatorname{Im}\left(\int_{0}^{H} d\left[(U-c)h^{*}\frac{dh}{dy}\right]\right) =$$

= Im[$(U(H)-c)h^{*}(H)\lim_{y\to H}\frac{h(y)-h(H)}{y-H} -$
 $-(U(0)-c)h^{*}(0)\lim_{y\to 0}\frac{h(y)-h(0)}{y-0}$]

then the latter implies that the situation is possible that

$$\operatorname{Im}[(U(H)-c)h^{*}(H)\lim_{y\to H}\frac{h(y)-h(H)}{y-H}]\to 0\cdot\infty$$

and / or

$$\operatorname{Im}[(U(0)-c)h^{*}(0)\lim_{y\to 0}\frac{h(y)-h(0)}{y-0}]\to 0\cdot\infty$$

for the reason that the function dh/dy consists of a countable set of branches. Examples of these functions dh/dy represent logarithmic, inverse trigonometric and other functions.

Specifically, as the function df/dy is not contained in the formulation of the boundary value problem (21), then there is no way to select one or the other branch of functions df/dy and dh/dy uniquely. Therefore, all branches of the function dh/dy are equitable, so that the integral (25) must vanish for all countable set of the function dh/dybranches as a whole, and this is an occasion for the emergence of the type $0 \cdot \infty$ (26) uncertainty.

From the foregoing it follows that the functions h with the first order derivatives dh/dy, containing a countable set of branches, are not covered by the Miles theorem (24). It is these functions that will give the counter-examples to this theorem.

As a result, the Miles theorem (24)[2-4] is right not for all functions h (22), but only for their subclass with derivatives dh/dy, which consist of a finite number of branches. That's what says for the fact that: 1) the condition (24) of theoretical linear stability is not only sufficient but also necessary in nature, and besides with respect to the adjective partial class of small plane perturbations (5) in the form of normal waves (6), (7), (17), (23); 2) no contradictions between the Miles theorem[2-4] and the absolute theoretical linear instability of the steady-state flows (4), obtained in the present work.

By the way, if the investigated fluid is homogeneous in density (so that the Taylor-Goldstein equation becomes the Rayleigh equation, and the Miles theorem reduces to the Rayleigh theorem), then it is proved in the publications[11, 15] that the subclass of functions, which correspond to functions h (22) with the first order derivatives dh/dy (26), containing a countable set of branches, serves as a non-empty set.

5. Conclusions

In this article the problem on linear stability of steady-sta

te plane-parallel shear flows (4) in a continuously stratified in density inviscid incompressible fluid in the gravity field between two immovable impermeable solid parallel planes in the Boussinesq approximation is considered.

By the direct Lyapunov method, it is proved that these flows are absolutely unstable in the theoretical sense with respect to small plane perturbations (6), (7), (16).Constructi ve sufficient conditions (see on the inequalities of the relati ons system (14)) for the practical linear instability are deduced. A priory lower estimate (15) is constructed, which displays exponential in time growth of the considered small perturbations. The application field of the Miles theorem (24) is strictly described, and it is also found that, by its nature, this theorem is both sufficient and necessary statement.

It should be stressed that from the mathematical point of view the results of this work are, in the main, a priori, because the existence theorems of solutions to the studied initial-boundary value problems for systems of differential equations with partial derivatives have not been proved.

Finally, regarding the question of whether the mathemati cal model (1) of an ideal continuously stratified fluid in the Boussinesq approximation describes the steady-state plane-parallel shear flows (4) in the gravity field adequately, it must be said that it is not adequate, since this model has no theoretically stable solutions (4), which would correspond to the steady-state plane-parallel shear flows, although this kind of flows is observed in nature and is realized in applications.

However, if conditions (refer to inequalities of the equations system (14)) of the practical linear instability are not met, the stationary solutions (4) to the mixed problem (1) will be stable with respect to small plane perturbations (6), (7), (16) in the form of normal waves (17) on those or any other finite time intervals.

It follows that the mathematical model (1) does not adequ ately characterize the steady-state plane-parallel shear flows (4) in the theoretical sense (at the semi-infinite intervals of time), but adequately — in the practical one (at the finite temporal intervals).

In the end, constructive sufficient conditions (see on ineq ualities of the equations system (14)) for the practical linear instability can provide with a foundation for the creation of effective method for managing of the steady-state flows (4) in the real-time mode [11, 16].

ACKNOWLEDGEMENTS

The study was supported by the Ministry of education and science of Russian Federation, project 14.B37.21.0355.

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